

IN THE CLAIMS

This listing of claims will replace all prior versions and listings of claims in the application.

1-8. **(Cancelled)**

9. **(Currently Amended)** A control system for an automotive vehicle and a trailer comprising:

means to determine the presence of the trailer;
a vehicle velocity sensor generating a vehicle velocity signal;
a steering wheel angle sensor generating a steering wheel angle signal; and
a controller coupled to the means, the velocity sensor and the steering angle sensor, said controller determining a rear axle side slip angle of the vehicle, and when the rear axle side slip angle is above a predetermined rear axle slip angle, the vehicle velocity signal is above a velocity threshold and the steering wheel angle is about zero, said controller programmed to apply brake-steer to the vehicle to stabilize the vehicle and trailer further in response to a reverse direction signal.

10-17. **(Cancelled)**

18. **(Currently Amended)** A control system as recited in claim 9 further comprising a yaw rate sensor generating a yaw rate signal, said controller programmed to apply brake-steer in further response to a [[reverse direction signal and]] yaw rate signal.

19. **(Currently Amended)** A control system as recited in claim 9 further comprising a steering wheel torque sensor generating a steering torque signal, said controller programmed to apply brake-steer in further response to a ~~[[reverse direction signal and]]~~ steering torque signal.

20-26. **(Cancelled)**